

Distinguished Lecture Series 2024/2025 Electricity Price Forecasting I

Rafał Weron*

(with Julia/Python notebooks coded and explained by Arkadiusz Lipiecki)

Department of Operations Research and Business Intelligence, Wrocław Tech, Poland https://p.wz.pwr.edu.pl/~weron.rafal



*Based on joint work with K.Bilińska, Y.Chawla, K.Chęć, A.Lipiecki, K.Maciejowska, W.Nitka, T.Serafin, B.Uniejewski, P.Zaleski (Wrocław Tech), C.Challu, K.Olivares (Nixtla), T.Hong (UNCC), K.Hubicka (UBS), A.Jędrzejewski (U.Aveiro), C.Kath (RWE), J.Lago (Amazon), G.Marcjasz (Alpiq), M.Narajewski (Statkraft), J.Nasiadka (Nokia), J.Nowotarski (BNY Mellon), H.Zareipour (U.Calgary), F.Ziel (U.Duisburg-Essen)

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Energy (load, price, wind & solar) forecasting* (Hong, Pinson, Wang, Weron, Yang & Zareipour, 2020, IEEE OAJPE)



Percentage of energy forecasting publications*

(Hong, Pinson, Wang, Weron, Yang & Zareipour, 2020, IEEE OAJPE)



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Competitive power market structures across the globe



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Power pool vs. power exchange

Power pool: one-sided auction



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Power exchange: two-sided auction

National vs. zonal vs. nodal pricing



Adapted from: National Grid ESO (2022) Net Zero Market Reform

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Power markets across the globe

North American landscape

Independent System Operators (ISO)

- Reliable & effective grid operation
- Scheduling of power generation
- Stability of supply (transmission)
- ERCOT (Texas) is a Regional Transmission Organization (RTO)
 - Does not cross state lines



ill Day-ahead (DA) and real-time (RT; ~5% of volume) markets

Nodal pricing

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European landscape

Transmission System Operators (TSO)

- Operate the transmission system
- Ensure the grid is balanced
- Exception: Germany has 4 TSOs
- Market coupling
 - Price Coupling of Regions EUPHEMIA (DA)
 - Flow-Based Market Coupling (DA)
 - XBID mechanism (ID)



ill Day-ahead (DA) and intraday (ID; 3-20% of volume) markets

Zonal pricing

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Market coupling \rightarrow (more) similar prices in bidding zones



Timeline of DA and ID trading activities in Europe

(Maciejowska, Uniejewski & Weron, 2023, Oxford Res. Enc.)



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Day-ahead (> 90% of papers) vs. intraday (real-time) markets (Maciejowska, Uniejewski & Weron, 2023, Oxford Res. Enc.)



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Introduction

Model taxonomy

Model taxonomy: 2014 vs. 2022

Weron (2014, IJF) \rightarrow Weron & Ziel (2022, DFG-NCN project PRIORITY)



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Day-ahead point forecasting: Univariate ... (Ziel & Weron, 2018, ENEECO)



Model taxonomy

... multivariate ...



... functional (data analysis) ...

(Chen & Li, 2017, JBES; Chen et al., 2019, Ann.Appl.Stat; Wang & Cao, 2023, Environmetrics)



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Model taxonomy

... or supply & demand curves?

(Ziel & Steinert, 2016, ENEECO → 'X-model'; Shah & Lisi, 2020, J.Forecasting)



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'Toy' mode

- 'Toy' models
 - The forecasting setup
 - Naive models
 - (Auto)regressive models
 - Nonlinear AR models
 - Exponential smoothing models
 - Supply stack models
- Beyond point forecasts

Forecast accuracy

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Forecasting setup: Fixed, expanding & rolling windows



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The forecasting setup

'Toy' models for point forecasts

• Let us fix the notation:

• $P_t = P_{24d+h} = P_{d,h}$ is the price for day d and hour h• $\hat{P}_t = \hat{P}_{d,h|d-1}$ is the forecast of $P_{d,h}$ computed on day d-1 (in the morning) where t = 1, ..., T, $d = 1, ..., \frac{T}{24}$ and h = 1, ..., 24

- The prediction error or residual is given by: $\varepsilon_t = P_t \hat{P}_t$
- Consider five classes of 'toy' models:
 - O Naive
 - (Auto)Regressive
 - Onlinear AR
 - Exponential smoothing
 - Supply stack

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Naive models

(Nogales et al., 2002, TPWRS; Weron, 2014, IJF; Lago et al., 2021, APEN)

• Naive (persistent, white noise) forecast:

$$\hat{P}_{d,h}^{ ext{naive}} = egin{cases} P_{d-1,h} & ext{for } d = ext{Tue, Wed, Thu, Fri} \ P_{d-7,h} & ext{for } d = ext{Mon, Sat, Sun} \end{cases}$$

- Simpler alternatives: $\hat{P}_{d,h}^{(1)} = P_{d-1,h}$ and $\hat{P}_{d,h}^{(7)} = P_{d-7,h}$
- $\hat{P}_{d,h}^{(7)}$ is easier to compute than $\hat{P}_{d,h}^{\text{naive}}$ and, unlike $\hat{P}_{d,h}^{(1)}$, captures weekly effects

Multiple regression

$$y_t = \beta_0 + \beta_1 x_{1,t} + \beta_2 x_{2,t} + \dots + \beta_k x_{k,t} + \varepsilon_t$$

- The predictors can be:
 - different variables, e.g., $x_{1,t}$ load, $x_{2,t}$ RES generation
 - lagged values of the same variable, e.g., $x_{1,t} = y_{t-1}$, $x_{2,t} = y_{t-2} \rightarrow \text{autoregression}$
 - or a combination of both
- Coefficients β_1, \ldots, β_k measure the marginal effects
 - after taking account of the effect of all other predictors
- The forecast \hat{y}_t of y_t is obtained by setting $\varepsilon_t = 0$

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(Ordinary) Least Squares (OLS) estimation

• The OLS chooses β_i 's that minimize the sum of squared errors (SSE):

$$\hat{\boldsymbol{\beta}} = \underset{\beta_i}{\operatorname{argmin}} \sum_{t=1}^{T} \varepsilon_t^2 = \underset{\beta_i}{\operatorname{argmin}} \sum_{t=1}^{T} (y_t - \underbrace{(\beta_0 + \beta_1 x_{1,t} + \beta_2 x_{2,t} + \ldots + \beta_k x_{k,t})}_{\hat{y}_t})^2$$

- The estimated coefficients are denoted by $\hat{m{eta}} = [\hat{m{eta}}_0, \dots, \hat{m{eta}}_k]$
- The process of finding $\hat{\beta}_i$'s is called:
 - estimating model parameters
 - fitting the model to the data
 - learning (training) the model

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Regression in matrix form

• The multiple regression model for t = 1, ..., T

$$y_t = \beta_0 + \beta_1 x_{1,t} + \beta_2 x_{2,t} + \dots + \beta_k x_{k,t} + \varepsilon_t$$

• Can be written in matrix form with OLS solution:

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon} \implies \hat{\boldsymbol{\beta}} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$$

where $\mathbf{y} = (y_1, \dots, y_T)', \ \boldsymbol{\varepsilon} = (\varepsilon_1, \dots, \varepsilon_T)', \ \boldsymbol{\beta} = (\beta_0, \dots, \beta_k)'$ and
$$\mathbf{X} = \begin{bmatrix} 1 & x_{1,1} & x_{2,1} & \dots & x_{k,1} \\ 1 & x_{1,2} & x_{2,2} & \dots & x_{k,2} \\ \vdots & \vdots & \vdots & \vdots \\ 1 & x_{1,T} & x_{2,T} & \dots & x_{k,T} \end{bmatrix}$$

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(Auto)regressive models

Expert ARX-type models

Consider an autoregressive structure with exogenous variables:

$$P_{d,h} = \beta_0 + \underbrace{\sum_{i=1}^{7} \beta_i P_{d-i,h}}_{\text{AutoRegressive effects}} + \underbrace{\sum_{i=1}^{7} \beta_{i+7} D_i}_{D_1 = \text{Mon, ...}} + \underbrace{\sum_{i=1}^{K} \beta_{i+14} X_{d,h}^{(i)}}_{\text{eXogenous variables}} + \varepsilon_{d,h}$$

• There can be no more dummies than categories \rightarrow set $\beta_0 = 0$ if all D_i 's are used

• Also set $\beta_0 = 0$ if the mean is removed from $P_{d,h}$ beforehand

- Special cases:
 - Naive model $P_{d,h}^{(1)}$ for $\beta_1 = 1$ and $\beta_{i\neq 1} = 0$
 - AR(7), sparse AR(7) with some AR lags missing
 - ARX(7) with $K \ge 1$, sparse ARX(7) with some AR lags missing

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Nonlinear AR models

Linear regression vs. single-output (shallow) neural network (Jędrzejewski, Lago, Marcjasz & Weron, 2022, IEEE-PEM)



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What are the differences?

- Computational complexity
 - Linearity \Leftrightarrow non-linearity (hidden layers)
- Optimization
 - **OLS** \Leftrightarrow *back-propagation*, Levenberg-Marquardt algorithm, ...
- Execution time (in MATLAB)
 - **Fast** \Leftrightarrow slow ... ca. 400× slower for one run!

0.061 vs. 24.57 sec. for 7 days on a laptop with i7-1065G7

- Stability
 - Always the same parameters/forecasts ⇔ different for each run, dependent on starting parameters
 - Solution: committee machines \rightarrow ensemble averaging

Number of hidden neurons vs. forecast accuracy (Marcjasz, Uniejewski & Weron, 2019, IJF)

- The higher are the price fluctuations (\rightarrow larger errors) the more neurons are needed
- ... but the dependence is not constant over time (seasonality)



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Number of runs (ensemble size) vs. forecast accuracy (Marcjasz, Uniejewski & Weron, 2019, IJF)

- The more runs (\rightarrow longer computational time) the better
- The prediction error decays as a power law



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Additive Holt-Winters method: Component form

Forecast eq.:
$$\hat{y}_{t+h|t} = \ell_t + hb_t + s_{t+h-m(k+1)}$$

Smoothing equations:
$$\begin{cases} \ell_t = \alpha(y_t - s_{t-m}) + (1 - \alpha)(\ell_{t-1} + b_{t-1}) & \text{Level} \\ b_t = \beta(\ell_t - \ell_{t-1}) + (1 - \beta)b_{t-1} & \text{Trend} \\ s_t = \gamma(y_t - \ell_t) + (1 - \gamma)s_{t-m} & \text{Seasonality} \end{cases}$$

where

- *h* is the forecast horizon (steps ahead), *m* is the period
- k is the integer part of $\frac{h-1}{m} \Rightarrow$ estimates come from the final period of the sample

 $0 \leqslant \alpha, \beta, \gamma \leqslant 1$ are estimated numerically by minimizing the sum of squared errors:

$$\sum_{t=1}^{I} \varepsilon_t^2 = \sum_{t=1}^{I} (y_t - \hat{y}_t)^2$$

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The family of exponential smoothing methods

(Hyndman & Athanasopoulos, 2021, OTexts; Hyndman, Koehler, Ord & Snyder, 2008, Springer)

Trend Component	Seasonal Component		
	N	Α	М
	(None)	(Additive)	(Multiplicative)
N (None)	(N,N)	(N,A)	(N,M)
A (Additive)	(A,N)	(A,A)	(A,M)
A _d (Additive damped)	(A_d,N)	(A_d,A)	(A_d, M)

Some of these methods we have already seen using other names:

Short hand	Method
(N,N)	Simple exponential smoothing
(A,N)	Holt's linear method
(A_d,N)	Additive damped trend method
(A,A)	Additive Holt-Winters' method
(A,M)	Multiplicative Holt-Winters' method
(A_d, M)	Holt-Winters' damped method

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Python snippet: ToyModels.ipynb

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Supply stack model (Weron & Ziel, 20**)

Fundamental approach from the subclass of parsimonious structural models

Assumptions:

- Island grid, i.e., no imports or exports
- The power plant park is composed of J units
- Every unit $j = 1, \ldots, J$ is characterized by its
 - installed capacity AC_j (in MW)
 - marginal cost MC_j (e.g., in EUR, USD) of producing an additional MWh by generator j



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Supply stack model cont.

(Weron & Ziel, 20**)

- Consider a park composed of J = 15 units
 - Roughly corresponds to Germany in 2018
 - 10 different types of generators
- The merit order curve is given by

 $MO(x) = MC_{j(x)}$

where x is the volume in MW and

- $j(x) = \max_{j} \{ CC_{j} \leq x \}$ is the marginal unit
- $CC_j = \sum_{i=1}^{j} AC_i$ is the cumulative capacity

j	AC _j	MC _j	Туре	CCj
1	8,000	0	CHP	8,000
2	6,000	0	Biomass	14,000
3	3,000	0	Hydro	17,000
4	8,000	0	Wind	25,000
5	4,000	0	Solar	29,000
6	10,000	10	Nuclear	39,000
7	11,000	20	Lignite	50,000
8	6,000	25	Lignite	56,000
9	9,000	30	Coal	65,000
10	6,000	35	Coal	71,000
11	7,000	45	NG	78,000
12	6,000	55	NG	84,000
13	4,000	65	NG	88,000
14	3,000	80	Oil	91,000
15	3.000	95	Oil	94,000

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Supply stack model: Price setting

Net demand of 53,000 MW yields a spot price of 25 EUR/MWh



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Point forecasts of 3 simple models: Germany, Sun 30.07.2017

Naive $\hat{P}_{d,h}^{\text{naive}}$, sparse AR(7; lags = 1,2,7, dummies = Mon, Sat, Sun), and the supply stack model



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Beyond point forecasts

- Beyond point forecasts
 - Probabilistic forecasts
 - Reliability & sharpness
 - Postprocessing point forecasts
 - Historical simulation
 - Conformal prediction

Forecast accuracy



Probabilistic (interval, density) forecasting (Gneiting & Katzfuss, 2014, Annu Rev)

We cannot observe the true underlying distribution \Rightarrow we cannot compare the *predictive* distribution \hat{F} with the actual one F ... only with past observations

Gneiting et al. (2007a, 2007b, 2014) argue that probabilistic forecasting aims to 'maximize the **sharpness** of the predictive distributions, subject to **reliability**'



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Reliability (calibration, unbiasedness)

- Refers to the statistical consistency between \hat{F} and the observations
- If a 90% PI covers 90% of the observed prices, then this PI is said to be:
 - reliable (Pinson et al., 2007; Pinson & Kariniotakis, 2010)
 - well calibrated (Gneiting et al., 2007a, 2007b, 2014)
 - unbiased (Taylor, 1999)

• Example: 13 o or 'misses' and 155 o or 'hits' \rightarrow the coverage is $\frac{155}{168} \approx 92\%$



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Sharpness

(Pinson et al., 2007, Wind En; Gneiting & Raftery, 2007, JASA; Gneiting & Katzfuss, 2014, Annu Rev)

- Refers to the concentration or tightness of the predictive distributions
 - Derives from the idea that reliable predictive distributions of null width correspond to perfect point predictions
 - Reliability is a joint property of the predictions and the observations
 - Sharpness is a property of the forecasts only



Postprocessing point forecasts

(Vannitsem et al., 2018, Elsevier; Chen et al., 2024, Ann Appl Stat; Lipiecki et al., 2024, ENEECO)





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The 'normal' benchmark

- Assume that the prediction errors are $N(\mu, \sigma^2)$ -distributed
- Training corresponds to estimating $\hat{\mu}$ and $\hat{\sigma}$ of $\varepsilon_t = y_t \hat{y}_t$ for $t \in S$
 - S is the training set (or calibration window)
- The τ -th quantile conditional on \hat{y}_t is obtained via:

$$\hat{q}_{\tau|\hat{y}_t} = \hat{y}_t + \hat{\mu} + \hat{\sigma} F_N^{-1}(\tau)$$

where $F_N^{-1}(\tau)$ is the inverse of the standard normal CDF, i.e., with $\mu = 0, \sigma = 1$

Historical simulation

(Hendricks, 1996, EPR; Alexander, 2008, Wiley; Nowotarski & Weron, 2018, RSER)

• A model-independent approach that computes

$$\hat{q}_{ au|\hat{y}_t} = \hat{y}_t + Q_{ au}(arepsilon_t)$$

where $Q_{\tau}(\varepsilon_t)$ is the sample τ -quantile of $\varepsilon_t = y_t - \hat{y}_t$ for $t \in S$

- The term historical simulation (HS) can be traced back to the early 1990s and the beginnings of Value-at-Risk (VaR)
- Similar to bootstrapped residuals (see, e.g., Hyndman & Athanasopoulos, 2021, FPP3), but each ε_t is sampled exactly once

FEDERAL RESERVE BANK of NEW YORK

ECONOMIC POLICY REVIEW Evaluation of Value-at-Risk Models Using Historical Data

April 1996Volume 2, Number 1 JEL classification: G11, G15, G28



Author: Darryll Hendricks

Recent studies have underscored the need for market participants to develop reliable methods of measuring risk. One increasingly popular technique is the use of 'value-at-risk' models, which convey estimates of market risk for an entire portfolio in one number. The author explores how well these models actually perform by applying twelve value-at-risk approaches to 1,000 randomly chosen foreign exchange portfolios. Using nine criteria to evaluate model performance, he finds that the approaches generally capture the risk that they set out to assess and tend to produce risk estimates that are similar in average size. No approach, however, appears to be superior by every measure.

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Conformal prediction

(Vovk et al., 2005, Springer; Kath & Ziel, 2021, IJF; Lipiecki et al., 2024, ENEECO)

• For $t \in S$ calculate the so-called non-conformity scores $\lambda_t = |\varepsilon_t| = |y_t - \hat{y}_t|$, then compute

$$\hat{q}_{ au \mid \mathsf{haty}_t} = \hat{y}_t - \mathbb{1}_{ au \leqslant 0.5} Q_{2 au}(\lambda) + \mathbb{1}_{ au \geqslant 0.5} Q_{2(1- au)}(\lambda)$$

where $Q_{\tau}(\lambda)$ is the au-th sample quantile of λ_t

- This version is called inductive or split CP, however, a 'split' is not needed if \hat{y}_t 's are already available
- HS works with ε_t 's, CP with $|\varepsilon_t|$'s \rightarrow symmetric \hat{F}
- Using ε₁,...,ε_T, HS approximates the whole distribution, CP only the positive half → smoother F̂



Python snippet: UncertaintyQuantification.ipynb

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Forecast accuracy

Introduction

2 'Toy' models

3 Beyond point forecasts

Forecast accuracy

- Absolute and square errors
- Percentage errors
- Scaled and relative errors
- Testing for coverage
- CRPS and the pinball score
- DM-type tests

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IIF Lecture: Electricity Price Forecasting, part I

Measures of (point) forecast accuracy

(Hyndman & Koehler, 2006, IJF; Weron, 2014, IJF; Kolassa, 2020, IJF; Lago et al., 2021, APEN)

• Mean Absolute Error

$$\mathsf{MAE} = rac{1}{T} \sum_{t=1}^{T} |arepsilon_t|$$

• (Root) Mean Square(d) Error

$$\mathsf{MSE} = \frac{1}{T} \sum_{t=1}^{T} \varepsilon_t^2 \quad \text{and} \quad \mathsf{RMSE} = \sqrt{\frac{1}{T} \sum_{t=1}^{T} \varepsilon_t^2}$$

where $|\varepsilon_t| = |P_t - \hat{P}_t|$ is the absolute and $\varepsilon_t^2 = (P_t - \hat{P}_t)^2$ is the square(d) error

Note: MSE is minimized by the mean, but MAE by the median
 ⇒ when using OLS measure forecast accuracy with MSE, not MAE

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Percentage errors: MAPE and DMAE

• Mean Absolute Percentage Error

$$\mathsf{MAPE} = \frac{1}{T} \sum_{t=1}^{T} \frac{|\varepsilon_t|}{P_t}$$

where $\frac{|\varepsilon_t|}{P_t}$ is the absolute percentage error can be used to compare across datasets • MAPE works well when $P_t \gg 0$, e.g., in load forecasting

- Is unreliable for electricity prices or temperatures (can be $\leqslant 0)$
- Instead of dividing by P_t we can divide by the daily mean $\overline{P_{24}} = \frac{1}{24} \sum_{t=1}^{24} P_t$ to obtain the Daily-weighted MAE for day d:

$$\mathsf{DMAE}_{d} = \frac{1}{24} \frac{1}{\overline{P_{24}}} \sum_{t=1}^{24} |\varepsilon_{t}| = \frac{1}{24} \frac{1}{\overline{P_{24}}} \sum_{h=1}^{24} |\varepsilon_{d,h}|$$

Percentage errors

Percentage errors: Symmetric MAPE (sMAPE)

See also https://robjhyndman.com/hyndsight/smape

- MAPE puts a heavier penalty on negative than on positive ε_t
- Makridakis (1993) proposed the 'symmetric MAPE':

$$\mathsf{sMAPE}_M = \frac{200}{T} \sum_{t=1}^T \frac{|\varepsilon_t|}{|P_t + \hat{P}_t|} = \frac{200}{T} \sum_{t=1}^T \frac{|P_t - \hat{P}_t|}{|P_t + \hat{P}_t|}$$

- Armstrong's (1985) version had no $|\cdot|$ in the denominator
- Both have a problem when $|P_t + \hat{P}_t| pprox 0$
- Chen & Yang (2004) defined it as (also dropped the '100'):

$$\mathsf{sMAPE}_{CY} = \frac{2}{T} \sum_{t=1}^{T} \frac{|\varepsilon_t|}{|P_t| + |\hat{P}_t|} = \frac{2}{T} \sum_{t=1}^{T} \frac{|P_t - \hat{P}_t|}{|P_t| + |\hat{P}_t|}$$

• Still, it is undefined when $P_t = \hat{P}_t = 0$

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Scaled errors

(Hyndman & Koehler, 2006, IJF)

• The Mean Absolute Scaled Error is defined by:

$$\mathsf{MASE} = \frac{1}{T} \sum_{t=\tau+1}^{T} \frac{|\varepsilon_t|}{e_m} = \frac{1}{T \cdot e_m} \sum_{t=\tau+1}^{T} |\varepsilon_t|$$

where

- $e_m = \frac{1}{\tau m} \sum_{t=m+1}^{\tau} |P_t P_{t-m}|$ is the MAE of a naive prediction on the training set
- *m* is the period for seasonal data (e.g., m = 4 for quarterly)
- Interpretation: if MASE < 1 then our prediction is better than naive (on the training set), if MASE > 1 then it is worse

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Relative errors

(Hyndman & Koehler, 2006, IJF; Lago et al., 2021, APEN)

- MASE is problematic when:
 - forecasting methods use different calibration windows / training sets
 - *P_t* exhibits 'long' periods of higher/lower values
- Lago et al. (2021, APEN) argue the a better metric is the relative MAE:

$$\mathsf{rMAE} = \mathsf{reIMAE} = \frac{\mathsf{MAE}_{\textit{method}}}{\mathsf{MAE}_{\textit{benchmark}}}$$

- The benchmark can be a naive model (as in MASE)
- Can easily be applied to other metrics, e.g., the RMSE
- Interpretation: if rMAE, rRMSE < 1 then our prediction is better than the benchmark, if rMAE, rRMSE > 1 then it is worse

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Unconditional coverage (UC)



• (Empirical) coverage is measured by

$$I_t = \begin{cases} 1 & \text{if } P_t \in \mathsf{PI} \to \mathsf{o} \text{ 'hit'} \\ 0 & \text{if } P_t \not\in \mathsf{PI} \to \mathsf{o} \text{ 'miss'} \end{cases}$$

and should match the nominal rate

$$\mathbb{P}(P_t \in \mathsf{PI}) = \mathbb{P}(I_t = 1) = (1 - \alpha)$$

• Some studies report only the so-called PI Coverage Probability

$$\mathbf{PICP} = \frac{1}{T} \sum_{t=1}^{T} I_t \cdot 100\%$$

• Other subtract it from the nominal coverage to obtain the so-called Average Coverage Error

 $\textbf{ACE} = \mathsf{PICP} - \mathsf{PINC}$

where PINC - PI Nominal Coverage

UC and the Kupiec test

(Kupiec, 1995, J Derivatives)

- Checks whether ACE = 0 or $\mathbb{P}(I_t = 1) = (1 \alpha)$, given that \circ are independent
 - Equivalent to testing that I_t is i.i.d. Bernoulli with mean (1α)
 - ullet Rejects the null ('good PI') if the percent of misses is statistically different from α
- The likelihood ratio statistics for unconditional coverage:

$$LR_{UC} = -2 \log \left\{ rac{(1-c)^{n_0} c^{n_1}}{(1-\pi)^{n_0} \pi^{n_1}}
ight\} \sim \chi^2(1)$$

- $c = (1 \alpha)$ is the nominal coverage rate
- $\pi = \frac{n_1}{n_0 + n_1}$ is the percentage of o 'hits'
- n_0 and n_1 are respectively the number of 0's and 1's in I_t

Independence, conditional coverage and the Christoffersen test (Christoffersen, 1998, IER)

- In the Kupiec (1995) test the clustering of o 'misses' does not matter, only the total number of violations plays a role
- Christoffersen (1998) introduced the Independence and Conditional Coverage tests
- Ind is tested against an explicit first-order Markov alternative
 - Like LR_{UC} , also $LR_{Ind} \sim \chi^2(1)$
- CC is simply a joint test for Ind and UC
 - If we condition on the first observation, then

$$LR_{CC} = LR_{UC} + LR_{Ind} \sim \chi^2$$
(2)

Rafał Weron (Wrocław Tech, PL)

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$\ensuremath{\mathsf{CRPS}}$ and the pinball score

Continuous Ranked Probability Score (CRPS)

(Gneiting & Raftery, 2007, JASA; Gneiting & Katzfuss, 2014, Annu Rev; Nitka & Weron, 2023, ORD)

• The CRPS is the standard metric for evaluating probabilistic forecasts:

$$\mathsf{CRPS}(\hat{F}, x) = \int_{-\infty}^{\infty} \left(\hat{F}(y) - \mathbb{1}_{\{x \leq y\}}\right)^2 dy$$

where \hat{F} is the predictive distribution and x is the observation, e.g., electricity price

- It is a proper scoring rule, i.e., quoting the true distribution as the forecast is an optimal strategy in expectation
- Problem: in practice we often work with a finite set of quantile forecasts

CRPS and the pinball score

(Gneiting & Raftery, 2007, JASA; Nowotarski & Weron, 2018, RSER; Nitka & Weron, 2023, ORD)

• The CRPS can be approximated by:

$$CRPS(\hat{F}, x) \approx \frac{2}{M} \sum_{i=1}^{M} PS(\hat{q}, x, q_i)$$

where

q₁ < ... < q_M is an equidistant dense grid of probabilities, e.g., 99 percentiles
q̂ ≡ F̂⁻¹(q) is the quantile forecast for quantile level q ∈ (0,1)
and the pinball score is defined as:

$$\mathsf{PS}(\hat{q}, x, q) = \left(\mathbbm{1}_{\{x < \hat{q}\}} - q\right)(\hat{q} - x)$$

• Note: The scaling factor of 2 is usually omitted in practice

Pinball score (or loss) in more detail

$$\mathsf{PS}\left(\hat{q}, x, q\right) = \left(\mathbbm{1}_{\{x < \hat{q}\}} - q\right)\left(\hat{q} - x\right) = \begin{cases} (1 - q)\left(\hat{q} - x\right) & \text{for } x < \hat{q} \\ q\left(x - \hat{q}\right) & \text{for } x \geqslant \hat{q} \end{cases}$$

- Also known as the quantile score, check function or the linlin/bilinear/newsboy loss
- For an Aggregate PS (or APS) average:
 - across all t in the test period
 - across all quantiles $\rightarrow \text{CRPS}$



Testing for equal predictive performance (Diebold & Mariano, 1995, JBES; Diebold, 2015, JBES)

• When faced with forecasts from two (or more) models we can rank them based on some score function (the lower the better):

$$\hat{S} = \frac{1}{T} \sum_{t=1}^{T} S(\hat{F}, x)$$

- But if we want to know whether the forecasts of model 1 are significantly better (more accurate) than those of model 2, then we need to use a test
- The most popular is the **DM test** for unconditional predictive ability

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Testing for equal predictive performance cont.

- The test of Giacomini & White (2006, Econometrica) accounts for parameter estimation uncertainty and tests conditional predictive ability (CPA)
- DM and GW tests can be used for nested and non-nested models if the calibration window does not grow with sample size (Giacomini & Rossi, 2013)
- This:
 - rules out expanding windows
 - 😁 admits fixed and rolling windows

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Testing for equal predictive performance cont.

- Model confidence set of Hansen et al. (2011, Econometrica) is similar to DM
- But uses bootstrap to approximate the distribution of the test statistics
- Forecast encompassing of Harvey et al. (1998, JBES)
- The null says that the forecasts of model 1 do not include more information than those of model 2

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Diebold-Mariano (DM) test

• It is an asymptotic *z*-test with null that the mean of the loss differential series:

$$d_t = S_1(\hat{F}, P_t) - S_2(\hat{F}, P_t)$$

is zero, where $S_i(\cdot, \cdot)$ is the score function for model *i*, e.g., $|\varepsilon_t|$, ε_t^2 , Pinball score

• How to use it? Compute the Diebold-Mariano statistic for t = 1, ..., T:

$$\mathsf{DM} = \sqrt{\mathcal{T}} rac{\hat{\mu}_{d_t}}{\hat{\sigma}_{d_t}}$$

where $\hat{\mu}_{d_t}$ and $\hat{\sigma}_{d_t}$ are the mean and standard deviation of d_t

• The null hypothesis of no differences is equivalent to $H_0: \mathbb{E}(d_t) = 0$

Diebold-Mariano (DM) test cont.

- If d_t is covariance stationary, the DM test statistics is asymptotically normal
- In practice we test twice, using one-sided tests with alternatives
 - $H_1: \mathbb{E}(d_t) < 0$, i.e., forecasts of model 1 are **better** than those of model 2
 - H_1^R : $\mathbb{E}(d_t) > 0$, i.e., forecasts of model 1 are worse than those of model 2

e.g., at the $\alpha = 5\%$ significance level

- Due to intraday correlation of electricity prices we test:
 - For each hour: $S_{i,h}^r(\hat{P}_{d,h}, P_{d,h}) = |P_{d,h} \hat{P}_{d,h}|^r$
 - Jointly for 24h: $S_i^r(\hat{P}_d, P_d) = \sum_{h=1}^{24} |P_{d,h} \hat{P}_{d,h}|^r$
- The DM test compares forecasts, not models! Critical value Reject Ho Reject Ho $\Rightarrow H_1^R$ is true \Rightarrow H_1 is true Test statistic ・ロト ・ 同ト ・ ヨト ・ ヨ UNC Charlotte, ISEA2025, 3-4.03.2025 61/63

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Python snippet: DieboldMariano.ipynb

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Articles & working papers on https://p.wz.pwr.edu.pl/~weron.rafal/Publ

Rafał Weron

Professor of Management Science (Energy Forecasting)

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K. Maciejowska, B. Uniejewski, R. Waron (2023) Forecasting electricity prices, in "Oxford Research Encyclopedia of Economics and Finance", Oxford University Press, DOI: 10.1093/acrefore/9780190625679.013.667. Working paper version available from arXiv: https://doi.org/10.48550/ arXiv.2204.11735



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